# Hyperboloid as Ruled Surface 

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When our daughter-in-law made wheat shocks as center-pieces for her fall-themed wedding reception, I naturally could not help pointing out the age-old observation that they represented a hyperboloid of one sheet (Figure 1). This was naturally greeted with the usual groans, but the thought stayed with me as I realized I had never proved this mathematically to myself.

The way the wheat shocks were made follows the timehonored way of making a string or wire model of the hyperboloid, as shown in Figure 2 ([1]). Namely, strings or wires are stretched vertically between two flat disks. The disks are twisted in opposite directions, yielding the subsequent images with increased twisting. A red line superimposed over one of the strings shows the amount of deviation from the vertical the string makes as the disks are twisted. A horizontal cross-section of the surface represented by the strings is a circle, indicated in green in the figures.


Figure 1 Wheat shock centerpiece


Figure 2 Twisting a cylinder of strings into a hyperboloid
Two mathematical concepts are involved here: a ruled surface and a hyperboloid of one sheet.

## Ruled Surface

The intuitive notion of a ruled surface involves a curve and a line moving along the curve sweeping out a two-dimensional ribbon-like shape as it bobs and twists along the curve. Figure 3 is an illustration of a ruled surface where the curve is shown in green and the line (segment) is shown in red.

As can be seen from Figure 2, a cylinder is an example of a ruled surface where a vertical line moves around a closed curve (circle in this case) keeping the same angle with respect to the curve and


Figure 3 A generic ruled surface not twisting as it moves. The end picture in Figure 2 suggests that the surface we are interested in is also a ruled surface, and that in fact it is a hyperboloid of one sheet. The point of this note is to prove this mathematically.

## Hyperboloid of One Sheet

But first we need to define what a hyperboloid of one sheet is. It is the locus of points $(x, y, z)$ in 3-dimensional space satisfying the equation

$$
\begin{equation*}
\frac{x^{2}}{a^{2}}+\frac{y^{2}}{b^{2}}-\frac{z^{2}}{c^{2}}=1 \tag{1}
\end{equation*}
$$

where $a, b$, and $c$ are constants (see Figure 4). Notice that the (green) points on the hyperboloid in the xy-plane (where $z=0$ ) satisfy the equation for an ellipse:

$$
\frac{x^{2}}{a^{2}}+\frac{y^{2}}{b^{2}}=1
$$

and likewise any horizontal slice parallel to the $x y-$ plane intersects the hyperboloid in an ellipse with proportionately larger semimajor and semiminor axes (a and b, resp.). Similarly, the (red) points on the hyperboloid in the xz-plane (where $y=0$ ) satisfy the equation for a hyperbola

$$
\frac{x^{2}}{a^{2}}-\frac{z^{2}}{c^{2}}=1
$$



Figure 4 Hyperboloid of one sheet

Furthermore, we will assume the ellipse is a circle, that is, $a=b$. This more closely reflects the situation shown in Figure 2 and the wheat shock. Notice this means the hyperboloid is obtained by rotating the hyperbola (red curve) around the z -axis so that it is a surface of revolution. To simplify matters further we shall assume the radius of the circle is one and that $c=1$ as well. So now we are considering the hyperboloid

$$
\begin{equation*}
x^{2}+y^{2}-z^{2}=1 \tag{2}
\end{equation*}
$$

and wish to show it is a ruled surface. Actually we shall proceed from the opposite direction by considering a ruled surface swept out by a line tilted to a $45^{\circ}$ angle and moving around a circle of radius 1 (as modeled in Figure 2). We shall show it defines the hyperboloid given in equation (2).

## Solution

Figure 5 shows an arbitrary point $(x, y, z)$ on the ruled surface. It also shows the (red) generating line that passes through it from the (green) generating curve (circle). We wish to show ( $x, y, z$ ) satisfies equation (2). Drop a perpendicular from the point down to the xy-plane. The length is $z$. Draw the line from the origin out to the foot of the perpendicular at $(x, y)$. The length of this line is designated $r$ and satisfies


Figure 5 3D view

$$
r^{2}=x^{2}+y^{2}
$$

Extend the tangent to the circle at the point of intersection of the generating line with the generating circle to the foot of the perpendicular at $(x, y)$ (see also Figure 6). The length of this line is designated $s$. From Figure 5 we can see that because the generating line makes an angle of $45^{\circ}$ with the xy-plane we have $s=z$. Since a tangent to a circle is perpendicular to the radius at the point of tangency, we also have

$$
s^{2}=r^{2}-1=x^{2}+y^{2}-1
$$

Hence,

$$
z^{2}=s^{2}=x^{2}+y^{2}-1
$$



Figure 6 2D view
which is the same as equation (2), and we are done.

If we removed the restriction that the circle be of radius 1 and let it be any radius, and if we allowed the generating line to be tilted to any other angle than $45^{\circ}$, we would still get a hyperboloid of one sheet. This time it would be of the form

$$
x^{2}+y^{2}-A z^{2}=B
$$

where $A$ and $B$ are constants (see [2], p.88). Investigating whether we would still get a hyperboloid if the generating curve were a general ellipse rather than a circle is a bit more complicated and I have not explored that yet.

I want to emphasize that this result is remarkable in a couple of ways. It is evident from Figure 2 that the resulting surface from the twisting is curved in some way, but it is not obvious that it should be a hyperboloid. The vertical crosssections could be some other type of curve than a hyperbola. They could be cycloids or catenaries or some shape without an equation. Furthermore, the notion that a highly curved surface could be made up of straight lines is both marvelous and mysterious, and can lead to some amazing applications. Consider the example in Figure 7 ([3], p.216) where hyperboloidal gears allow drive shafts to meet at angles other than perpendicular or parallel.

## References.

[1] Based on diagrams from the website https://sites.google.com/site/simeonlapinbleu/hyperboloid


Figure 7 Hyperboloidal gears transmit motion to a skew shaft (Retrieved 12/12/2012)
[2] Kühnel, Wolfgang, Differential Geometry: Curves - Surfaces - Manifolds, $2^{\text {nd }}$ Edition, Student Mathematical Library, Vol. 16, American Mathematical Society, 2006.
[3] Gardner, Martin, "Hyperbolas," in Penrose Tiles to Trapdoor Ciphers ... and the return of Dr. Matrix, rev, MAA, 1997, pp.205-217
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